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MAT 380 Presentation  
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September 26, 2012

## Laplace Transformations

A method of solving linear differential equations with constant coefficients is to perform a **Laplace transform**. This method takes a linear initial value problem and transforms its differential equation into an algebraic one. The transformation method works by taking the domain of the independent variable (call it the  $t$ -domain) into a new domain (the  $s$ -domain) where  $t$  is usually real and  $s$  is complex.

**Laplace transform:** The transformation of a given function  $f(t)$ , which is denoted by  $\bar{f}(s) = L\{f\}(s)$ , is defined in terms of an integral by

$$\bar{f}(s) = L\{f\}(s) = \int_0^{\infty} f(t) e^{-st} dt. \quad (1)$$

Clearly, the Laplace Transform  $L\{f\}$  takes a function  $f(t)$  with independent variable  $t$  and returns a function  $\bar{f}(s)$  with the independent variable  $s$ . From the definition (1) we immediately obtain the linear rule

$$\overline{af + bg}(s) = a\bar{f}(s) + b\bar{g}(s), \quad (2)$$

where  $a$  and  $b$  are constants and  $f$  and  $g$  are functions.

### **Laplace Transform of a first derivative:**

Assume that a given function  $y \equiv y(t)$  satisfies  $y(t)e^{-kt} \rightarrow 0$  and  $y'(t)e^{-kt} \rightarrow 0$  as  $t \rightarrow \infty$  for some constant  $k$ . The Laplace Transform of the first derivative  $dy/dt$  of  $y \equiv y(t)$  is obtained by using (1) and is written

$$L\left\{\frac{dy}{dt}\right\}(s) = \int_0^{\infty} \frac{dy}{dt} e^{-st} dt.$$

By integration by parts we have

$$L\left\{\frac{dy}{dt}\right\}(s) = [y e^{-st}]_0^{\infty} - \int_0^{\infty} y (-s) e^{-st} dt$$

or

$$L\left\{\frac{dy}{dt}\right\}(s) = -y(0) + s \int_0^{\infty} y e^{-st} dt. \quad (3)$$

But notice that the integral on the right-hand side is now itself the Laplace Transform of  $y$ . So (2) becomes

$$L\left\{\frac{dy}{dt}\right\}(s) = -y(0) + s L\{y\}(s).$$

This is abbreviated to

$$L\left\{\frac{dy}{dt}\right\} = s \bar{y} - y(0). \quad (4)$$

### Table of Laplace Transforms

Function: in the $t$ -domain	Laplace Transform: in the $s$ -domain
$f(t)$	$L\{f(t)\} \equiv \bar{f}(s)$
$y (\equiv y(t))$	$\bar{y} (\equiv \bar{y}(s))$
$\frac{dy}{dt}$	$s \bar{y} - y(0)$
$\frac{d^2 y}{dt^2}$	$s^2 \bar{y} - s y(0) - y'(0)$
$k$	$\frac{k}{s}$
$e^{\alpha t}$	$\frac{1}{s - \alpha}, \quad \text{Re}(s - \alpha) > 0$
$\sin \beta t$	$\frac{\beta}{s^2 + \beta^2}$
$\cos \beta t$	$\frac{s}{s^2 + \beta^2}$
$t^n$	$\frac{n!}{s^{n+1}}$
$e^{\alpha t} g(t)$	$\bar{g}(s - \alpha), \quad \text{Re}(s - \alpha) > 0$

where, in the table above,  $k$ ,  $\alpha$  and  $\beta$  are constants and  $n$  is a positive integer.

## **Significance**

In the field of circuitry, Laplace transforms derive circuit equations from the time domain (the  $t$ -domain) to the  $s$ -domain. This analysis of linear time-invariant systems can also be applied to harmonic oscillators, optical devices and mechanical systems. The ability of Laplace transforms to take the time-domain and transform to the frequency-domain takes inputs and outputs of time and changes them to functions of complex angular frequency (measured in radians per unit time). This method is another way to analyze a system's behavior in a simplified manner.